

# A Comparison of Various Bipolar Transistor Biasing Circuits

An up-to-date review of bias techniques

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The bipolar junction transistor (BJT) is often used as a low noise amplifier in cellular, PCS and pager applications because of its low cost. With a minimal number of external matching networks, the BJT can produce an LNA with RF performance considerably better than an MMIC. Of equal importance is the DC performance. Although the device's RF performance may be quite closely controlled, the variation in device DC parameters can be quite significant because of normal process variations.

It is not unusual to find a 2 or 3 to 1 ratio in device  $h_{FE}$ . Variation in  $h_{FE}$  from device to device will generally not appear as a difference in RF performance. In other words, two devices with widely different  $h_{FE}$  can have similar RF performance, as long as the devices are biased at the same  $V_{CE}$  and  $I_C$ . The primary purpose of the bias network is to keep  $V_{CE}$  and  $I_C$  constant as DC parameters vary from device to device.

The bias circuitry is often overlooked because of its apparent simplicity. With a poorly designed fixed bias circuit, the variation in  $I_C$  from lot to lot can have the same maximum to minimum ratio as the  $h_{FE}$  variation from lot to lot. If there is no compensation  $I_C$  will double when  $h_{FE}$  is doubled. It is the task of the DC bias circuit to maximize the circuit's tolerance to  $h_{FE}$  variations. In addition, transistor parameters can vary over temperature causing a drift in  $I_C$  at temperature. The low power supply voltages typically available for handheld applications also make it more difficult to design a temperature stable bias circuit.

One solution to the biasing dilemma is the use of active biasing. Active biasing often makes use of an IC or a PNP transistor and a variety of resistors, effectively setting  $V_{CE}$  and  $I_C$  regard-

less of variations in device  $h_{FE}$ . Although the technique of active biasing would be the best choice for control of device to device variability and over temperature variations, associated costs are usually high.

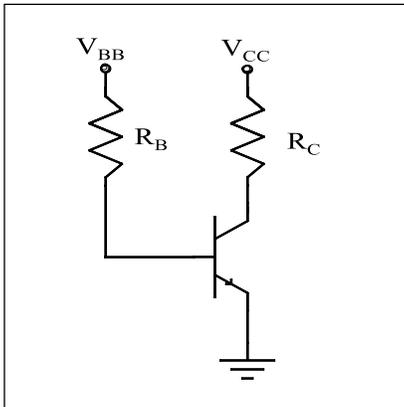
Other biasing options include various forms of passive biasing. This article discusses various passive biasing circuits, including their advantages and disadvantages.

## Various BJT passive bias circuits

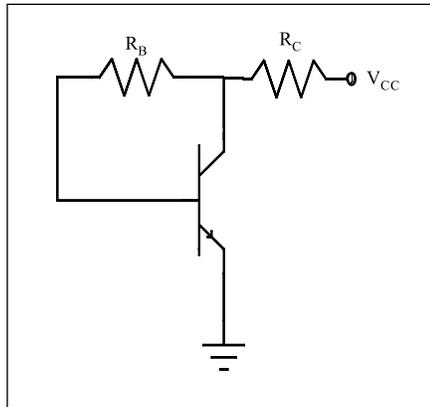
Passive biasing schemes usually consist of two to five resistors properly arranged about the transistor. Various passive biasing schemes are shown in Figure 1. The simplest form of passive biasing is shown as Circuit #1 in Figure 1. The collector current  $I_C$  is simply  $h_{FE}$  times the base current  $I_B$ . The base current is determined by the value of  $R_B$ . The collector voltage  $V_{CE}$  is determined by subtracting the voltage drop across resistor  $R_C$  from the power supply voltage  $V_{CC}$ . As the collector current is varied, the  $V_{CE}$  will change based on the voltage drop across  $R_C$ . Varying  $h_{FE}$  will cause  $I_C$  to vary in a fairly direct manner. For constant  $V_{CC}$  and constant  $V_{BE}$ ,  $I_C$  will vary in direct proportion to  $h_{FE}$ . For example, as  $h_{FE}$  is doubled, collector current,  $I_C$ , will also double. Bias circuit #1 provides no compensation for variation in device  $h_{FE}$ .

Bias circuit #2 provides voltage feedback to the base current source resistor  $R_B$ . The base current source is fed from the voltage  $V_{CE}$ , as opposed to the supply voltage  $V_{CC}$ . The value of the base bias resistor  $R_B$  is calculated based upon nominal device  $V_{BE}$  and the desired  $V_{CE}$ . Collector resistor  $R_C$  has both  $I_C$  and  $I_B$  flowing through it.

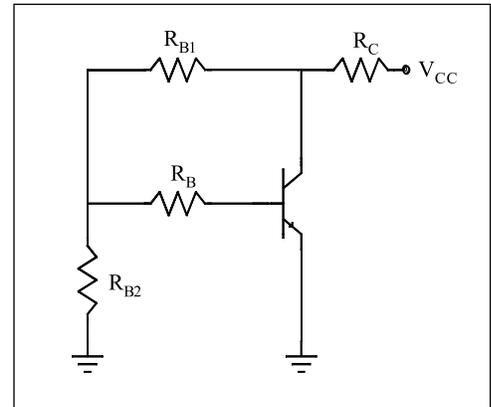
The operation of this circuit is best explained



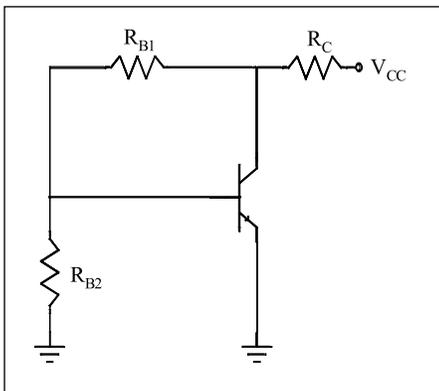
▲ Figure 1(a). Circuit #1: nonstabilized BJT bias network.



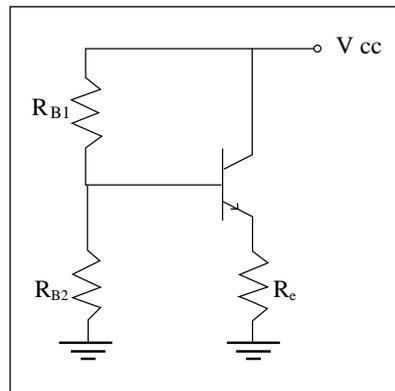
▲ Figure 1(b). Circuit #2: voltage feedback BJT bias network.



▲ Figure 1(c). Circuit #3: voltage feedback with current source BJT bias network.



▲ Figure 1(d). Circuit #4: voltage feedback with voltage source BJT bias network.



▲ Figure 1(e). Circuit #5: emitter feedback BJT bias network.

exception that the series current source resistor  $R_B$  is omitted. This circuit is seen in bipolar power amplifier design with resistor  $R_{B2}$  replaced by a series silicon power diode providing temperature compensation for the bipolar device. The current flowing through resistor  $R_{B1}$  is shared by both resistor  $R_{B2}$  and the base emitter junction  $V_{BE}$ . The greater the current through resistor  $R_{B2}$ , the greater the regulation of the base emitter voltage  $V_{BE}$ .

Bias circuit #5 is the customary textbook circuit for biasing BJTs. A resistor is used in series with the device emitter lead to provide voltage feedback. This circuit ultimately provides the best control of  $h_{FE}$  variations from device to device and over temperature.

as follows. An increase in  $h_{FE}$  will tend to cause  $I_C$  to increase. An increase in  $I_C$  causes the voltage drop across resistor  $R_C$  to increase. The increase in voltage across  $R_C$  causes  $V_{CE}$  to decrease. The decrease in  $V_{CE}$  causes  $I_B$  to decrease because the potential difference across base bias resistor  $R_B$  has decreased. This topology provides a basic form of negative feedback which tends to reduce the amount that the collector current increases as  $h_{FE}$  is increased.

Bias circuit #3 has been discussed in past literature but predominately when very high  $V_{CC}$  ( $> 15$  volts) and  $V_{CE}$  ( $> 12$  volts) were used [1]. The voltage divider network consisting of  $R_{B1}$  and  $R_{B2}$  provide a voltage divider from which resistor  $R_B$  is connected. Resistor  $R_B$  then determines the base current.  $I_B$  times  $h_{FE}$  provides  $I_C$ . The voltage drop across  $R_C$  is determined by the collector current  $I_C$ , the base current  $I_B$  and the current consumed by the voltage divider, consisting of  $R_{B1}$  and  $R_{B2}$ . This circuit provides similar voltage feedback to that of bias circuit #2.

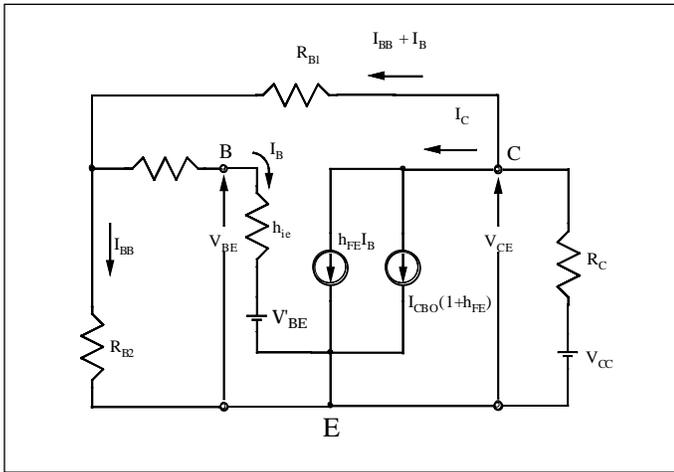
Bias circuit #4 is similar to bias circuit #3 with the

control of  $h_{FE}$  variations from device to device and over temperature. The disadvantage of this circuit is that the emitter resistor must be properly bypassed for RF. The typical bypass capacitor often has internal lead inductance which can create unwanted regenerative feedback. The feedback can create device instability. Despite the problems associated with using the emitter resistor technique, this biasing scheme generally provides the best control on  $h_{FE}$  and over temperature variations.

The sections that follow begin with a discussion of the BJT model and its temperature dependent variables. From the basic model, various equations are developed to predict the device's behavior over  $h_{FE}$  and temperature variations. This article is an update to the original article written by Kenneth Richter of Hewlett-Packard [2] and Hewlett-Packard Application Note 944-1 [3].

## BJT modeling

The BJT is modeled as two current sources, as shown in Figure 2. The primary current source is  $h_{FE}I_B$ . In parallel is a secondary current source  $I_{CBO}(1 + h_{FE})$  that



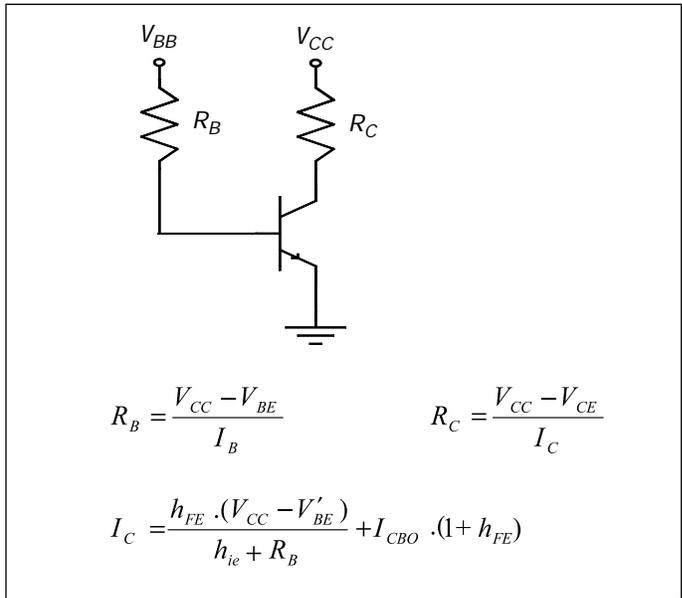
▲ Figure 2. Gummel-Poon model of BJT with voltage feedback and constant base current source network.

describes the leakage current flowing through a reverse biased PN junction.  $I_{CBO}$  is typically  $1 \times 10^{-7}$  A at 25 degrees C for an Agilent Technologies HBF0405 transistor.  $V_{BE}$  is the internal base emitter voltage with  $h_{ie}$  representing the equivalent Hybrid PI input impedance of the transistor.  $h_{ie}$  is also equal to  $h_{FE} / \lambda I_C$  where  $\lambda = 40$  at +25 degrees C.  $V_{BE}$  will be defined as measured between the base and emitter leads of the transistor. It is equivalent to  $V_{BE} + I_B h_{ie}$ .  $V_{BE}$  is approximately 0.78 volts at 25 degrees C for the HBF0405 transistor.

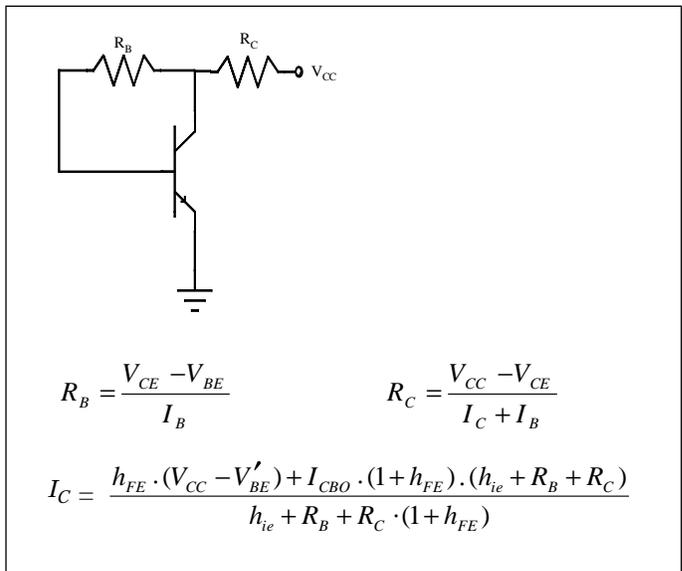
The device parameters that exhibit the greatest change as temperature is varied are  $h_{FE}$ ,  $V_{BE}$ , and  $I_{CBO}$ . These temperature dependent variables have characteristics which are process dependent and fairly well understood.  $h_{FE}$  typically increases with temperature at the rate of 0.5 percent/degrees C.  $V_{BE}$  has a typical negative temperature coefficient of -2 mV/degrees C. This indicates that  $V_{BE}$  decreases 2 mV for every degree increase in temperature.  $I_{CBO}$  typically doubles for every 10 degree C rise in temperature. Each one of these parameters contributes to the net resultant change in collector current as temperature is varied.

For each bias network shown in Figure 1, several sets of simplified circuit equations have been generated to allow calculation of the various bias resistors. These are shown in Figures 3, 4, 5, 6 and 7. Each of the bias resistor values are calculated based on various design parameters such as desired  $I_C$ ,  $V_{CE}$ , power supply voltage  $V_{CC}$  and nominal  $h_{FE}$ ,  $I_{CBO}$  and  $h_{ie}$  are assumed to be zero for the basic calculation of resistor values.

Additional information, usually provided by the designer, is required for the three circuits that use the voltage divider consisting of  $R_{B1}$  and  $R_{B2}$ . For the bias network that uses voltage feedback with current source, the designer must choose the voltage across  $R_{B2}$  ( $V_{RB2}$ ) and the bias current through resistor  $R_{B2}$ , which will be termed  $I_{RB2}$ . If  $V_{CE} > V_{RB2} > V_{BE}$ , then a suggested  $V_{RB2}$



▲ Figure 3. Equations for nonstabilized bias network.

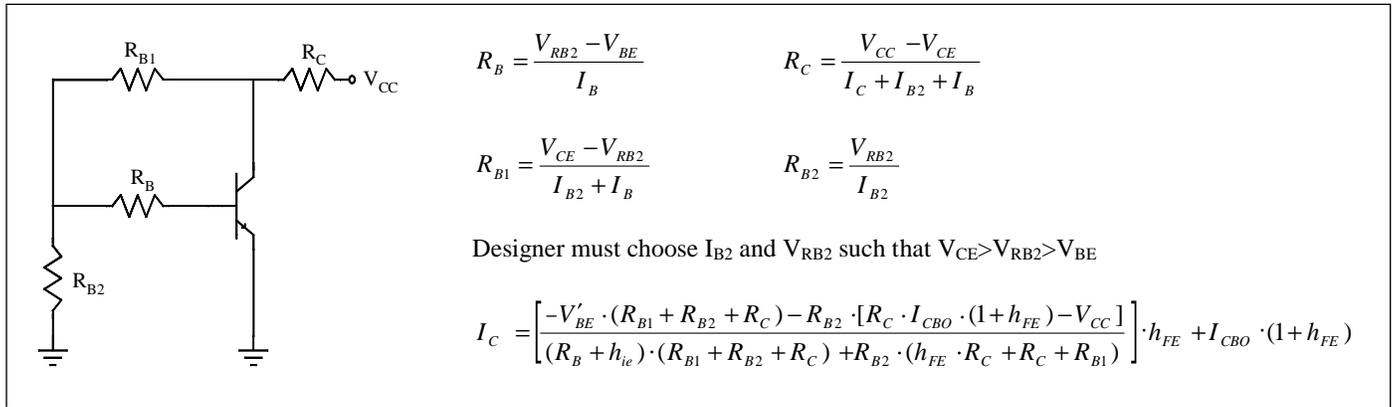


▲ Figure 4. Equations for voltage feedback bias network.

would be 1.5 volts and a suggested  $I_{RB2}$  would be 10 percent of  $I_C$ , or 0.5 mA.

The voltage feedback with a voltage source network and the emitter feedback network also require that the designer choose  $I_{RB2}$ . The ratio of  $I_C$  to  $I_{RB2}$  can play a major role in bias stability.

An equation was then developed for each circuit that calculates collector current,  $I_C$  based on nominal bias resistor values and typical device parameters, including  $h_{FE}$ ,  $I_{CBO}$ , and  $V_{BE}$ . MATHCAD 7 was used to help develop the  $I_C$  equation. Although the  $I_C$  equation begins simply, it develops into a rather lengthy equation



▲ Figure 5. Equations for voltage feedback with current source bias network.

for some of the more complicated circuits. MATHCAD helped to simplify this task.

### Design example using the Agilent HBFP-0405 BJT

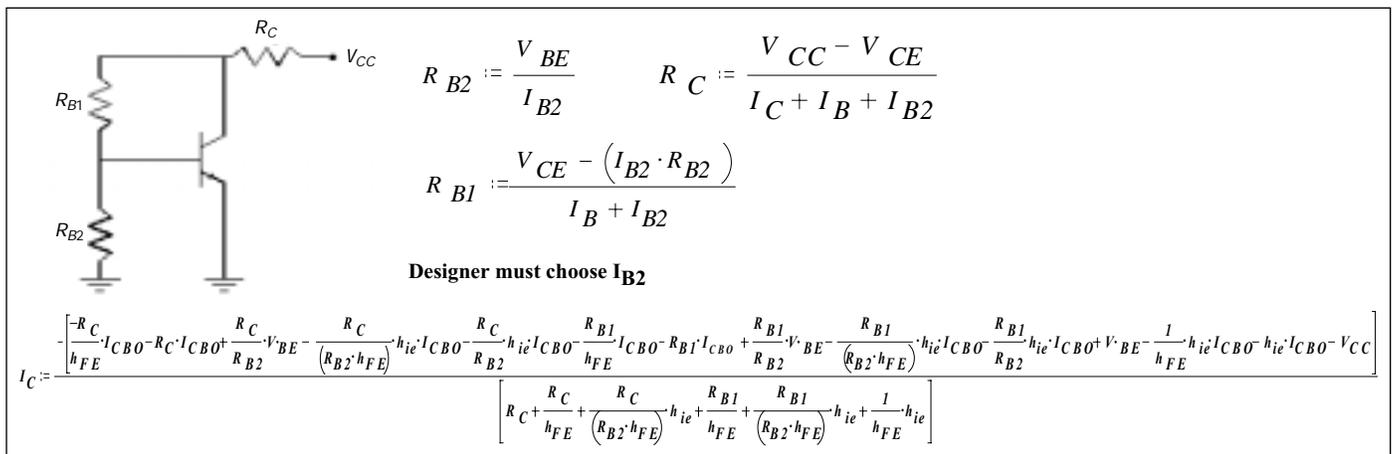
The HBFP-0405 transistor is used as a test example for each of the bias circuits. The HBFP-0405 is described in [4] as a low noise amplifier for 1800 to 1900 MHz applications. The HBFP-0405 will be biased at a  $V_{CE}$  of 2.7 volts and a drain current  $I_C$  of 5 mA. A power supply voltage of 3 volts will be assumed. The nominal  $h_{FE}$  of the HBFP-0405 is 80. The minimum is 50 while the maximum is 150. The calculated bias resistor values for each bias circuit are described in Table 1.

With the established resistor values,  $I_C$  is calculated based on minimum and maximum  $h_{FE}$ . The performance of each bias circuit with respect to  $h_{FE}$  variation is shown in Table 2. Bias circuit #1 clearly has no compensation for varying  $h_{FE}$ , allowing  $I_C$  to increase 85 percent as  $h_{FE}$  is taken to its maximum. Circuit #2 with very simple collector feedback offers considerable compensation due to  $h_{FE}$  variations allowing an increase of only 42 percent. Circuit #3 offers very little improvement over circuit #2. Circuit #4 provides considerable improvement in  $h_{FE}$  control by only allowing a 9 percent

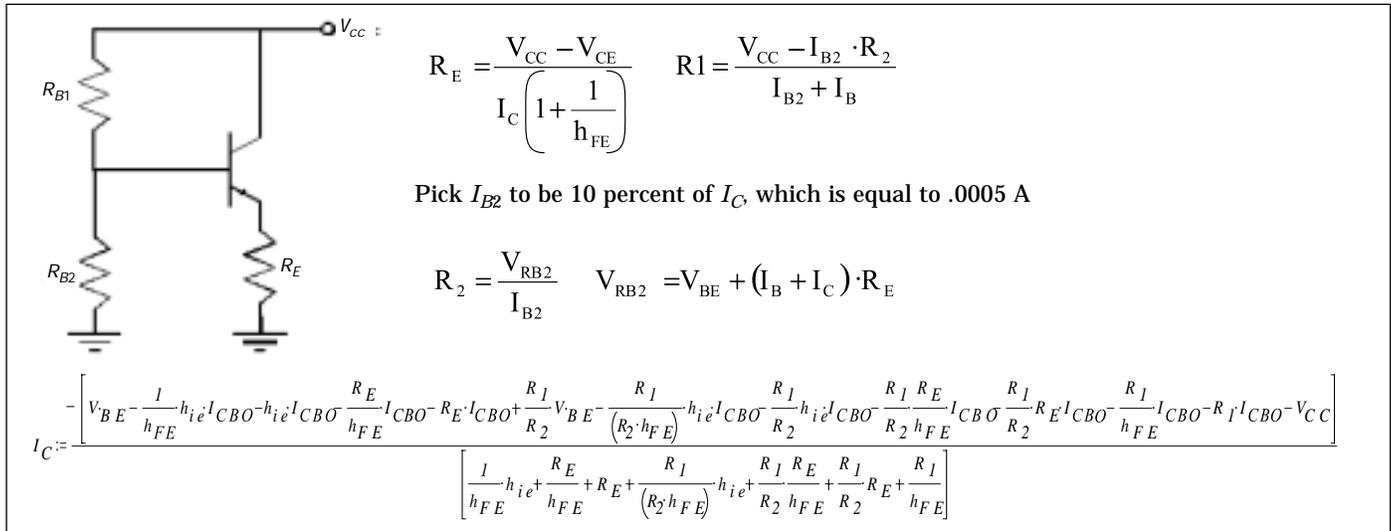
increase in  $I_C$ . Circuit #4 offers an improvement over the previous circuits by providing a stiffer voltage source across the base emitter junction. As we will see later, this circuit has worse performance over temperature as compared to circuits #2 and #3. However, when both  $h_{FE}$  and temperature are considered, circuit #4 will appear to be the best performer for a grounded emitter configuration. As expected, circuit #5 provides the best control on  $I_C$  with varying  $h_{FE}$  allowing only a 5.4 percent increase in  $I_C$ . Results are power supply dependent, and with higher  $V_{CC}$ , results may vary significantly.

### BJT performance over temperature

Since all three temperature dependent variables ( $I_{CBO}$ ,  $h_{FE}$  and  $V_{BE}$ ) exist in the  $I_C$  equation, differentiating the  $I_C$  equation with respect to each of the parameters provides insight into their effect on  $I_C$ . The partial derivative of each of the three parameters represents a stability factor. The various stability factors and their calculation are shown in Table 3. Each circuit has three distinctly different stability factors which are then multiplied times a corresponding change in either  $V_{BE}$ ,  $h_{FE}$ , or  $I_{CBO}$  and finally summed. These changes or deltas in  $V_{BE}$ ,  $h_{FE}$ , and  $I_{CBO}$  are calculated based on



▲ Figure 6. Equations for voltage feedback with voltage source bias network.



▲ Figure 7. Equations for emitter feedback bias network.

variations in these parameters based on the manufacturing processes.

A comparison of each circuit's stability factors will certainly provide insight as to which circuit compensates best for each parameter. MATHCAD was again

used to calculate the partial derivatives for each desired stability factor. The stability factors for bias circuit #1 are shown in Table 4. The stability factors for the remaining circuits are shown in the Appendix.

The change in collector current from the nominal

Resistor	Non-Stabilized Bias Network	Voltage Feedback Bias Network	Voltage Feedback with Current Source Bias Network	Voltage Feedback with Voltage Source Bias Network	Emitter Feedback Bias Network
$R_C$	140 $\Omega$	138 $\Omega$	126 $\Omega$	126 $\Omega$	
$R_B$	30770 $\Omega$	19552 $\Omega$	11539 $\Omega$		
$R_{B1}$			889 $\Omega$	2169 $\Omega$	2169 $\Omega$
$R_{B2}$			3000 $\Omega$	1560 $\Omega$	2960 $\Omega$
$R_E$					138 $\Omega$

▲ Table 1. Bias resistor values for HBFP-0405 biased at  $V_{CE} = 2$  volts,  $V_{CC} = 2.7$  volts,  $I_C = 5$  mA,  $h_{FE} = 80$  for the various bias networks.

Bias Circuit	Non-Stabilized Bias Network	Voltage Feedback Bias Network	Voltage Feedback with Current Source Bias Network	Voltage Feedback with Voltage Source Bias Network	Emitter Feedback Bias Network
$I_C$ (mA)@ minimum $h_{FE}$	3.14	3.63	3.66	4.53	4.70
$I_C$ (mA)@ typical $h_{FE}$	5.0	5.0	5.0	5.0	5.0
$I_C$ (mA)@ maximum $h_{FE}$	9.27	7.09	6.98	5.44	5.27
Percentage change in $I_C$ from nominal $I_C$	+85% -37%	+42% -27%	+40% -27%	+9% -9%	+5.4% -6%

▲ Table 2. Summary of  $I_C$  variation versus  $h_{FE}$  for various bias networks for the HBFP-0405,  $V_{CC} = 2.7$  volts,  $V_{CE} = 2$  volts,  $I_C = 5$  mA,  $T_j = +25$  degrees C.

design value at 25 degrees C is then calculated by taking each stability factor and multiplying it times the corresponding change in each parameter. Each product is then summed to determine the absolute change in collector current.

As an example, the collector current of the HBFP-0405 will be analyzed as temperature is increased from +25 degrees C to +65 degrees C. For the HBFP-0405,  $I_{CBO}$  is typically 100 nA at +25 degrees C and typically doubles for every 10 degrees C temperature rise. Therefore,  $I_{CBO}$  will increase from 100 nA to 1600 nA at +65 degrees C. The difference or  $\Delta I_{CBO}$  will be 1600 - 100 = 1500 nA. The 1500 nA will then be multiplied times its corresponding  $I_{CBO}$  stability factor.

$V_{BE}$  at 25 degrees C was measured at 0.755 volts for the HBFP-0405. Since  $V_{BE}$  has a typical negative temperature coefficient of -2 mV per degree C,  $V_{BE}$  will be 0.675 volts at +65 degrees C. The difference in  $V_{BE}$  will then be 0.675 - 0.755 = -0.08 volts. The -0.08 volts will then be multiplied by its corresponding  $V_{BE}$  stability factor.

$I_{CBO} = \frac{\partial I_C}{\partial I_{CBO}} \quad h_{FE}, V_{BE} = \text{constant}$	First calculate the stability factors for $V_{BE}$ , $I_{CBO}$ and $h_{FE}$ . Then, to find the change in collector current at any temperature, multiply the change from 25 degrees C of each temperature dependent variable with its corresponding stability factor and sum.
$V_{BE} = \frac{\partial I_C}{\partial V_{BE}} \quad I_{CBO}, h_{FE} = \text{constant}$	
$h_{FE} = \frac{\partial I_C}{\partial h_{FE}} \quad I_{CBO}, V_{BE} = \text{constant}$	
$\Delta I_C = S I_{CBO} \times \Delta I_{CBO} + S V_{BE} \times \Delta V_{BE} + S h_{FE} \times \Delta h_{FE}$	

▲ Table 3. Calculation of the stability factors and their combined effect on  $I_C$ .

Collector Current at any Temperature ( $I_C$ )	$\frac{h_{FE} \cdot (V_{CC} - V'_{BE})}{(h_{ie} + R_B)} + I_{CBO} \cdot (1 + h_{FE})$
$I_{CBO}$ Stability Factor $I_{CBO} = \frac{\partial I_C}{\partial I_{CBO}}  _{h_{FE}, V_{BE} = \text{constant}}$	$1 + h_{FE}$
$V_{BE}$ Stability Factor $V_{BE} = \frac{\partial I_C}{\partial V_{BE}}  _{I_{CBO}, h_{FE} = \text{constant}}$	$\frac{-h_{FE}}{h_{ie} + R_B}$
$h_{FE}$ Stability Factor $h_{FE} = \frac{\partial I_C}{\partial h_{FE}}  _{I_{CBO}, V_{BE} = \text{constant}}$	$\frac{V_{CC} - V'_{BE}}{h_{ie} + R_B} + I_{CBO}$

▲ Table 4. Stability factors for non-stabilized bias network #1.

$h_{FE}$  is typically 80 at +25 degrees C and typically increases at a rate of 0.5 percent per degree C. Therefore,  $h_{FE}$  will increase from 80 to 96 at +65 degrees C, making  $\Delta h_{FE}$  equal to  $96 - 80 = 16$ . Again the  $\Delta$  is multiplied by its corresponding stability factor.

Once all stability terms are known, they can be summed to give the resultant change in collector current from the nominal value at +25 degrees C. The results of the stability analysis are shown in Table 5. The nonsta-

Bias Circuit	Non-stabilized	#2 Voltage Feedback	#3 Voltage Feedback w/Current Source	#4 Voltage Feedback	#5 Emitter Feedback
$I_{CBO}$ stability factor	81	52.238	50.865	19.929	11.286
$V_{BE}$ stability factor	$-2.56653 \times 10^{-3}$	$-2.568011 \times 10^{-3}$	$-3.956 \times 10^{-3}$	-0.015	$-6.224378 \times 10^{-3}$
$h_{FE}$ stability factor	$6.249877 \times 10^{-5}$	$4.031 \times 10^{-5}$	$3.924702 \times 10^{-5}$	$1.537669 \times 10^{-5}$	$8.707988 \times 10^{-6}$
$\Delta I_C$ due to $I_{CBO}$ (mA)	0.120	0.078	0.076	0.030	0.017
$\Delta I_C$ due to $V_{BE}$ (mA)	0.210	0.205	0.316	1.200	0.497
$\Delta I_C$ due to $h_{FE}$ (mA)	0.999	0.645	0.628	0.246	0.140
Total $I_C$ (mA)	1.329	0.928	1.020	1.476	0.654
Percentage change in $I_C$ from nominal $I_C$	26.6%	18.6%	20.4%	29.5%	13.1%

▲ Table 5. Bias stability analysis at +65 degrees C using the HBFP-0405, where  $V_{CC} = 2.7$  volts,  $V_{CE} = 2$  volts and  $I_C = 5$  mA.

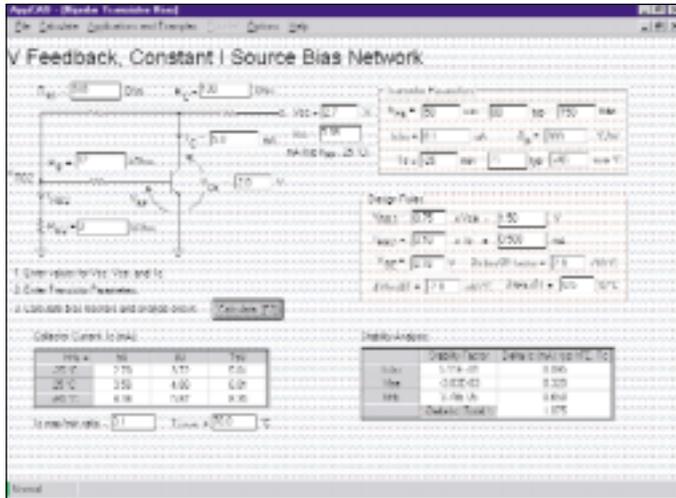
bilized circuit #1 allows  $I_C$  to increase about 27 percent, while circuits 2 and 3 show a 19 to 20 percent increase in  $I_C$ . Somewhat surprising is that circuit #4 shows a nearly 30 percent increase in  $I_C$  with temperature because  $V_{BE}$  is the major contributor to stability. This is probably due to the impedance of the  $R_{B1}$  and  $R_{B2}$  voltage divider working against  $V_{BE}$ . Both circuits #2 and #3 have very similar performance over temperature. Both offer a significant improvement over circuit #1 and #4. Predictably, circuit #5 offers the best performance over temperature by nature of the emitter feedback. Emitter feedback can be used effectively if the resistor can be adequately RF bypassed without producing stability problems.

The degree of control that each bias circuit has on controlling  $I_C$  due to  $h_{FE}$  variations and the intrinsic temperature dependent parameters is defined by the design of the bias circuit. Increasing the voltage differential between  $V_{CE}$  and  $V_{CC}$  can enhance the circuit's ability to control  $I_C$ . In handset applications, this becomes difficult with 3-volt batteries as power sources. The current that is allowed to flow through the various bias resistors can also have a major effect on  $I_C$  control.

In order to analyze the various configurations, an AppCAD [5] module was generated. AppCAD consists of various modules developed to help RF designers with microstrip, stripline, detector, pin diode, MMIC biasing, RF amplifier, transistor biasing and system level calculations, as well as other design modules. The AppCAD BJT biasing module allows the designer to fine-tune each bias circuit design for optimum performance. AppCAD also allows the designer to input device varia-

tion parameters peculiar to a certain manufacturer's semiconductor process. A sample screen showing a typical bias circuit is shown in Figure 8. The data from AppCAD is used to create the graphs in the following sections.

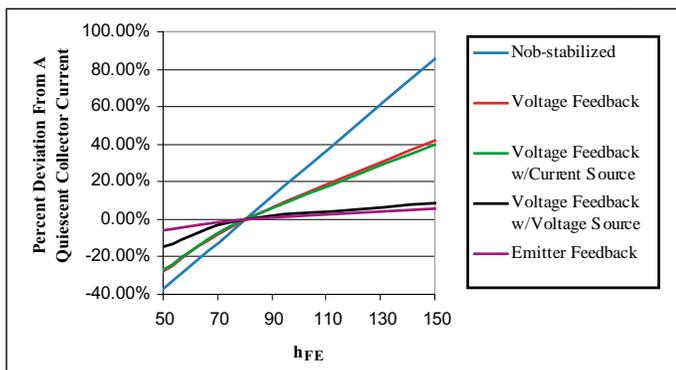
The first exercise is to graphically illustrate the percentage



▲ Figure 8. Agilent Technologies AppCAD module for BJT biasing.

change in  $I_C$  versus  $h_{FE}$ . AppCAD is used to calculate the resistor values for each of the five bias networks. The HBF0405 transistor is biased at a  $V_{CE}$  of 2 volts,  $I_C$  of 5 mA, and  $V_{CC}$  of 2.7 volts. Various values of  $h_{FE}$  are substituted into AppCAD; results are presented in Figure 9. The data clearly shows that the emitter feedback and voltage feedback with voltage source networks are superior to the remaining circuits with regards to controlling  $h_{FE}$  at room temperature. These networks provide a 4:1 improvement over the other two voltage feedback networks.

AppCAD is then used to simulate a temperature change from  $T_j = -25$  de-grees C to  $+65$  de-grees C with  $h_{FE}$  held constant. Whereas the original Matchcad analysis assumed that  $T_c = T_j$ , AppCAD takes into account that  $T_j$  is greater than  $T_c$ . AppCAD calculates the thermal rise based on DC power dissipated and the thermal impedance of the device. The results of the analysis are shown in Figure 10. The voltage feedback with voltage source network performed nearly as poorly as the non-stabilized circuit. This is due to the tempera-



▲ Figure 9. Percent change in quiescent collector current versus  $h_{FE}$  for the HBF0405 where  $V_{CC} = 2.7$  volts,  $V_{CE} = 2$  volts,  $I_C = 5$  mA and  $T_j = +25$  degrees C.

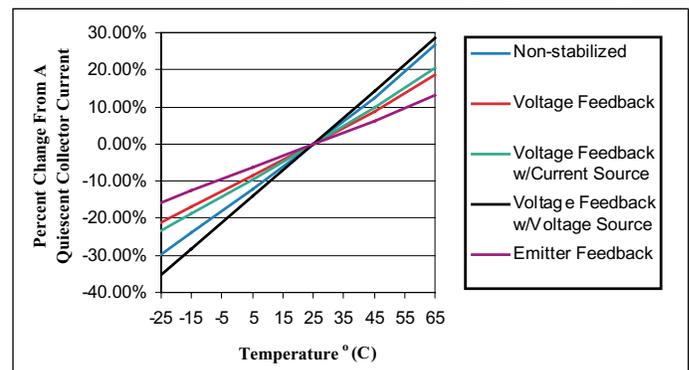
ture induced  $V_{BE}$  decrease and the bias circuit trying to keep  $V_{BE}$  constant. Power bipolar designers will often utilize a silicon diode in place of  $R_{B2}$  so that the bias voltage will track the  $V_{BE}$  of the transistor. Depending on the impedance of the voltage divider network,  $V_{BE}$  could rise, causing  $I_C$  to increase. The emitter feedback network performed very well as expected. The simple voltage feedback network appeared to be optimum when considering the simplicity of the circuit.

Bias networks 3 through 5 make use of an additional resistor that shunts some of the total power supply current to ground. Properly chosen, this additional bias current can be used to assist in controlling  $I_C$  over temperature and  $h_{FE}$  variations from device to device. AppCAD is set up such that the designer has various choices regarding the amount of bias resistor current that is allowed to flow from the power supply. AppCAD is used to analyze each bias circuit.

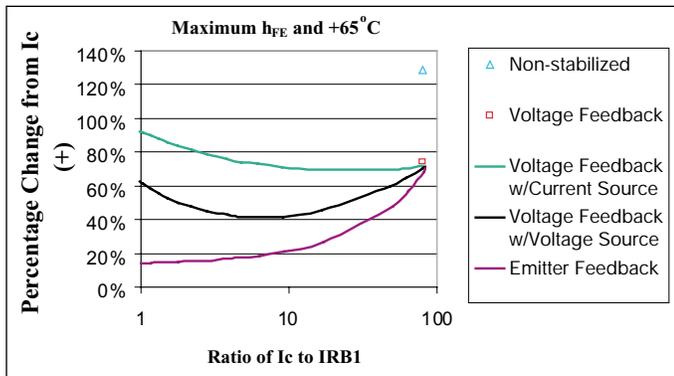
The graphs in Figures 11 and 12 plot the percentage change in  $I_C$  versus the ratio of  $I_C$  to  $I_{RB1}$ .  $I_{RB1}$  is the current flowing through resistor  $R_{B1}$ , which is the summation of base current  $I_B$  and current flowing through resistor  $R_{B2}$ . The maximum permissible ratio of  $I_C$  to  $I_{RB1}$  is limited by the  $h_{FE}$  of the transistor. Figure 11 represents the worst case condition, where  $I_C$  increases at maximum  $h_{FE}$  and highest temperature. Figure 12 shows the opposite scenario, in which the lowest  $I_C$  results from lowest  $h_{FE}$  and lowest temperature. The percentage change is certainly more pronounced at high  $h_{FE}$  and high temperature.

Although some of the predicted results are somewhat surprising, the bias network with emitter resistor feedback, as expected, offers the best performance overall. For a ratio of  $I_C$  to  $I_{RB1}$  of 10 to 1 or less, the resultant change in collector current is less than 20 percent. The voltage feedback with voltage source network performs best with an  $I_C$  to  $I_{RB1}$  ratio between 6 and 10 with a worst case change of 41 percent in collector current.

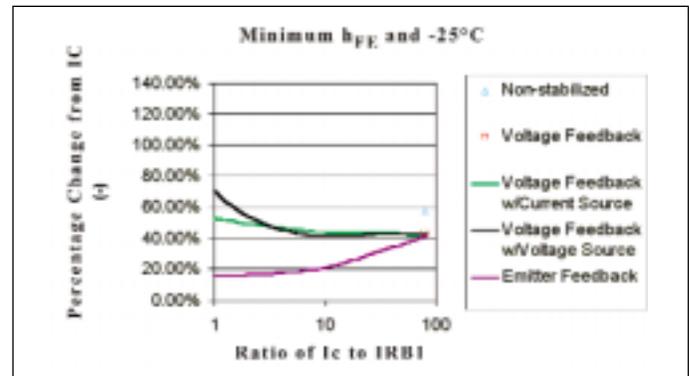
To complete the comparison, two additional points representing the nonstabilized and the voltage feedback networks have been added to the graphs. They are



▲ Figure 10. Percent change in quiescent collector current versus temperature for the HBF0405 where  $V_{CC} = 2.7$  volts,  $V_{CE} = 2$  volts,  $I_C = 5$  mA and  $T_j = +25$  degrees C.



▲ Figure 11. Percent change in quiescent collector current versus ratio of  $I_C$  to  $I_{RB1}$  for maximum  $h_{FE}$  and  $T_j = +65$  degrees C for the HBFP-0405, where  $V_C = 2.7$  volts,  $V_{CE} = 2$  volts and  $I_C = 5$  mA.



▲ Figure 12. Percent change in quiescent collector current versus ratio of  $I_C$  to  $I_{RB1}$  for minimum  $h_{FE}$  and  $T_j = -25$  degrees C for the HBFP-0405, where  $V_{CC} = 2.7$  volts,  $V_{CE} = 2$  volts and  $I_C = 5$  mA.

shown as single points because only the base current is in addition to the collector current. The nonstabilized network has an increase of 129 percent, while the voltage feedback network has an increase of 74.5 percent. The voltage feedback with current source network offers no benefit over the simpler voltage feedback network.

## Conclusion

This article discussed the circuit analysis of four commonly used stabilized bias networks and one nonstabilized bias network for the bipolar junction transistor. In addition to the presentation of the basic design equations for the bias resistors for each network, an equation was presented for collector current in terms of bias resistors and device parameters. The collector current equation was then differentiated with respect to the three primary temperature dependent variables resulting in three stability factors for each network. These stability factors plus the basic collector current equation give the designer insight as to how best bias transistors for best performance over  $h_{FE}$  and temperature variations. The basic equations were then integrated into an AppCAD module, providing the circuit designer with an easy and effective way to analyze bias networks for bipolar transistors. ■

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verting the bipolar biasing equations into a very effective and useful AppCAD module with which various bias networks can be easily designed and evaluated.

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## Appendix

Collector Current at any Temperature ( $I_C$ )	$\frac{h_{FE} \cdot (V_{CC} - V'_{BE}) + I_{CBO} \cdot (1 + h_{FE}) \cdot A}{h_{ie} + R_B + R_C \cdot (1 + h_{FE})}$
$I_{CBO}$ Stability Factor $I_{CBO} = \frac{\partial I_C}{\partial I_{CBO}} \Big _{h_{FE}, V_{BE} = \text{constant}}$	$\frac{(1 + h_{FE}) \cdot A}{h_{ie} + R_B + R_C \cdot (1 + h_{FE})}$
$V_{BE}$ Stability Factor $V_{BE} = \frac{\partial I_C}{\partial V_{BE}} \Big _{I_{CBO}, h_{FE} = \text{constant}}$	$\frac{-h_{FE}}{h_{ie} + R_B + R_C \cdot (1 + h_{FE})}$
$h_{FE}$ Stability Factor $h_{FE} = \frac{\partial I_C}{\partial h_{FE}} \Big _{I_{CBO}, V_{BE} = \text{constant}}$	$\frac{V_{CC} - V'_{BE} + A \cdot I_{CBO}}{h_{FE} \cdot R_C + R_B + h_{ie} + R_C} -$ $\frac{R_C \cdot h_{FE} \cdot (V_{CC} - V'_{BE} + A \cdot I_{CBO}) + A \cdot I_{CBO}}{(h_{FE} \cdot R_C + R_B + h_{ie} + R_C)^2}$ <p style="margin: 0;">where <math>A = h_{ie} + R_B + R_C</math></p>

▲ Stability factors for voltage feedback bias network #2.

Collector Current at any Temperature ( $I_C$ )	$h_{FE} \left[ \frac{-V_{BE} \cdot A - R_{B2} \cdot [R_C \cdot I_{CBO} \cdot (1 + h_{FE}) - V_{CC}]}{(R_B + h_{ie}) \cdot A + R_{B2} \cdot (h_{FE} \cdot R_C + R_C + R_{B1})} \right] + I_{CBO}(1 + h_{FE})$
$I_{CBO}$ Stability Factor $I_{CBO} = \frac{\partial I_C}{\partial I_{CBO}} \Big _{h_{FE}, V_{BE} = \text{constant}}$	$(1 + h_{FE}) - \frac{R_{B2} \cdot h_{FE} \cdot R_C \cdot (1 + h_{FE})}{A \cdot (R_B + h_{ie}) + R_{B2} \cdot (h_{FE} \cdot R_C + R_C + R_{B1})}$
$V_{BE}$ Stability Factor $V_{BE} = \frac{\partial I_C}{\partial V_{BE}} \Big _{I_{CBO}, h_{FE} = \text{constant}}$	$\frac{-h_{FE} \cdot A}{(R_B + h_{ie}) \cdot A + R_{B2} \cdot (h_{FE} \cdot R_C + R_C + R_{B1})}$
$h_{FE}$ Stability Factor $h_{FE} = \frac{\partial I_C}{\partial h_{FE}} \Big _{I_{CBO}, V_{BE} = \text{constant}}$	$\frac{h_{FE} \cdot \{R_{B2} \cdot R_C \cdot [(-R_{B2} \cdot V_{CC} + B) + R_{B2} \cdot R_C \cdot I_{CBO} \cdot (1 + h_{FE})]\}}{D^2}$ $\left[ \frac{B + R_{B2} \cdot [R_C \cdot I_{CBO} \cdot (1 + h_{FE}) - V_{CC} + h_{FE} \cdot R_C \cdot I_{CBO}]}{D} \right] + I_{CBO}$ <p style="margin: 0;">where</p> $A = R_{B1} + R_{B2} + R_C$ $B = V_{BE} \cdot (R_{B1} + R_{B2} + R_C)$ $C = (R_B + h_{ie}) \cdot (R_{B1} + R_{B2} + R_C)$ $D = (R_B + h_{ie}) \cdot (R_{B1} + R_{B2} + R_C) + R_{B2} \cdot (h_{FE} \cdot R_C + R_C + R_{B1})$

▲ Stability factors for voltage feedback with current source bias network #3.

<p>Collector Current at any Temperature (<math>I_C</math>)</p>	$\frac{I_{CBO} \cdot (-A) + I_{CBO} \cdot h_{ie} \cdot (-B) + D - V_{CC}}{C}$
<p><math>I_{CBO}</math> Stability Factor</p> $I_{CBO} = \frac{\partial I_C}{\partial I_{CBO}} \Big _{h_{FE}, V_{BE} = \text{constant}}$	$\frac{h_{ie} \cdot B + A}{C}$
<p><math>V_{BE}</math> Stability Factor</p> $V_{BE} = \frac{\partial I_C}{\partial V_{BE}} \Big _{I_{CBO}, h_{FE} = \text{constant}}$	$\frac{-\frac{R_C}{R_{B2}} - \frac{R_{B1}}{R_{B2}} - 1}{C}$
<p><math>h_{FE}</math> Stability Factor</p> $h_{FE} = \frac{\partial I_C}{\partial h_{FE}} \Big _{I_{CBO}, V_{BE} = \text{constant}}$	$\frac{I_{CBO} \cdot \left[ \frac{-R_C}{h_{FE}^2} - \frac{R_{B1}}{h_{FE}^2} \right] + I_{CBO} \cdot h_{ie} \cdot E}{C}$ $\frac{I_{CBO} \cdot A + I_{CBO} \cdot h_{ie} \cdot B - D + V_{CC}}{C^2} \cdot \left[ \frac{-R_C}{h_{FE}^2} - \frac{R_{B1}}{h_{FE}^2} + h_{ie} \cdot E \right]$ <p>where:</p> $A = \frac{R_C}{h_{FE}} + R_C + \frac{R_{B1}}{h_{FE}} + R_{B1}$ $B = \frac{R_C}{R_{B2} \cdot h_{FE}} + \frac{R_C}{R_{B2}} + \frac{R_{B1}}{R_{B2} \cdot h_{FE}} + \frac{R_{B1}}{R_{B2}} + \frac{1}{h_{FE}} + 1$ $C = R_C + \frac{R_C}{h_{FE}} + \frac{R_{B1}}{h_{FE}} + h_{ie} \cdot \left[ \frac{R_C}{R_{B2} \cdot h_{FE}} + \frac{R_{B1}}{R_{B2} \cdot h_{FE}} + \frac{1}{h_{FE}} \right]$ $D = \frac{R_C}{R_{B2}} \cdot V'_{BE} + \frac{R_{B1}}{R_{B2}} \cdot V'_{BE} + V'_{BE}$ $E = \frac{-R_C}{R_{B2} \cdot h_{FE}^2} - \frac{R_{B1}}{R_{B2} \cdot h_{FE}^2} - \frac{1}{h_{FE}^2}$

**▲ Stability factors for voltage feedback with voltage source bias network #4.**

<b>Collector Current at any Temperature (<math>I_C</math>)</b>	$\frac{h_{ie} \cdot I_{CBO} \cdot (-A) + I_{CBO} \cdot (-B) + D}{C}$
<b><math>I_{CBO}</math> Stability Factor</b>  $I_{CBO} = \frac{\partial I_C}{\partial I_{CBO}} \Big _{h_{FE}, V_{BE} = \text{constant}}$	$\frac{h_{ie} \cdot A + B}{C}$
<b><math>V_{BE}</math> Stability Factor</b>  $V_{BE} = \frac{\partial I_C}{\partial V_{BE}} \Big _{I_{CBO}, h_{FE} = \text{constant}}$	$\frac{-1 - \frac{R_1}{R_2}}{C}$
<b><math>h_{FE}</math> Stability Factor</b>  $h_{FE} = \frac{\partial I_C}{\partial h_{FE}} \Big _{I_{CBO}, V_{BE} = \text{constant}}$	$\frac{I_{CBO} \cdot E + h_{ie} \cdot I_{CBO} \cdot \left[ \frac{-1}{h_{FE}^2} - \frac{R_1}{R_2 \cdot h_{FE}^2} \right]}{C}$ $\frac{I_{CBO} \cdot B + h_{ie} \cdot I_{CBO} \cdot A - D}{C^2} \cdot \left[ h_{ie} \cdot \left( \frac{-1}{h_{FE}^2} - \frac{R_1}{R_2 \cdot h_{FE}^2} \right) + E \right]$ <p>where</p> $A = \frac{R_1}{R_2 \cdot h_{FE}} + \frac{R_1}{R_2} + \frac{1}{h_{FE}} + 1$ $B = \frac{R_1}{R_2} \cdot \frac{R_E}{h_{FE}} + \frac{R_1}{R_2} \cdot R_E + \frac{R_E}{h_{FE}} + R_E + \frac{R_1}{h_{FE}} + R_1$ $C = h_{ie} \cdot \left( \frac{1}{h_{FE}} + \frac{R_1}{R_2 \cdot h_{FE}} \right) + \frac{R_E}{h_{FE}} + R_E + \frac{R_1}{R_2} \cdot \frac{R_E}{h_{FE}} + \frac{R_1}{R_2} \cdot R_E + \frac{R_1}{h_{FE}}$ $D = V_{BE}' + \frac{R_1}{R_2} \cdot V_{BE}' - V_{CC}$ $E = \frac{-R_E}{h_{FE}^2} - \frac{R_1}{R_2} \cdot \frac{R_E}{h_{FE}^2} - \frac{R_1}{h_{FE}^2}$

▲ **Stability factors for emitter feedback bias network #5.**